Extreme Temperature Motor and Drill System, Phase II



Completed Technology Project (2005 - 2007)

Project Introduction

In response to the need for motors, actuators and drilling systems that can operate in the harsh venusian environment for extended periods of time, on the order of several hours to days, Honeybee Robotics proposes continued development of an extreme temperature motor and an extreme temperature drill system and demonstration of both in simulated Venus surface conditions. A first-generation prototype motor was designed, built and tested in Venus-like conditions (460

0

C temperature, mostly CO2 gas environment) during Phase I. The Phase I tests demonstrated the feasibility of the design through verification that the motor can operate at 460

O

C for an extended period of time. A further developed and optimized version of this motor could be used to actuate drills, robotic arms, and other devices outside of an environment-controlled landed platform on the surface of Venus. The motor's capability to survive for hours (and potentially longer) in that environment is a major benefit to future Venus science missions since it would allow time for communication ground loops to optimize drill target selection and allow for multiple samples to be acquired from the subsurface. An extreme temperature motor would therefore revolutionize the exploration of Venus. In Phase II, both an extreme environment motor and an extreme environment drill system will be developed to TRL 6. Aside from Venus exploration, other potential NASA and non-NASA applications for an extreme temperature motor include actuation of fluid pumps, gimbals, robotic joints and manipulation systems, as well as turbine, expendable launch vehicle and furnace tending system components.



Extreme Temperature Motor and Drill System, Phase II

Table of Contents

| Project Introduction | |
|-------------------------------|---|
| Organizational Responsibility | |
| Primary U.S. Work Locations | |
| and Key Partners | 2 |
| Project Management | |
| Technology Areas | 2 |

Organizational Responsibility

Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

Lead Center / Facility:

Jet Propulsion Laboratory (JPL)

Responsible Program:

Small Business Innovation Research/Small Business Tech Transfer

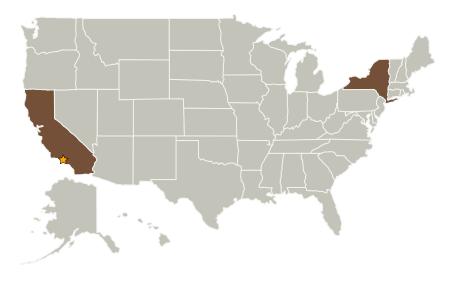


Extreme Temperature Motor and Drill System, Phase II



Completed Technology Project (2005 - 2007)

Primary U.S. Work Locations and Key Partners



| Organizations Performing Work | Role | Туре | Location |
|----------------------------------|--------------|----------|------------|
| | Lead | NASA | Pasadena, |
| | Organization | Center | California |
| Honeybee Robotics, | Supporting | Industry | Pasadena, |
| Ltd. | Organization | | California |

| Primary U.S. Work Locations | |
|-----------------------------|----------|
| California | New York |

Project Management

Program Director:

Jason L Kessler

Program Manager:

Carlos Torrez

Technology Areas

Primary:

- TX08 Sensors and Instruments
 - ☐ TX08.3 In-Situ
 Instruments and Sensors
 ☐ TX08.3.6 Extreme
 Environments Related
 to Critical System
 Health Management

